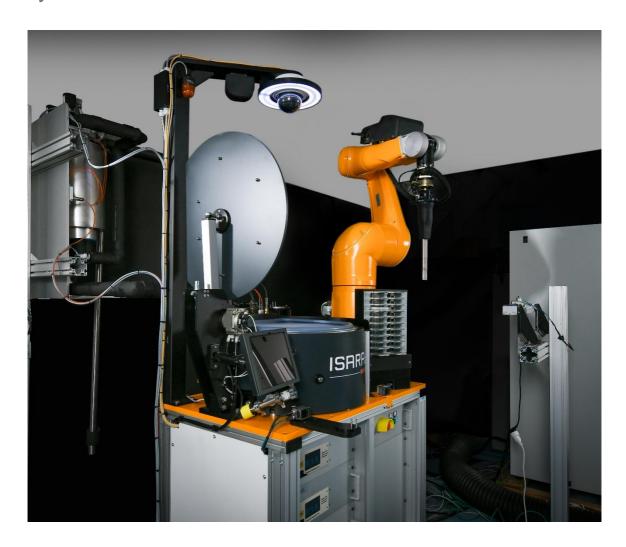


Fast, Reliable and User-friendly

Robotic Sample Changer for X-Ray Crystallography on Synchrotron Beamlines



precision in motion



© CMCF-ID beamline at the Canadian Light Source, Saskatoon



Reliability

- High precision automatic teaching and calibration
- High mechanical compliance and low thermal inertia gripper with sample detection
- Robust and field-proven software



High throughput

- Large storage capacity with a limited footprint
- Double gripper for fast sample transfer
- Simple interface adaptable to any Synchrotron beamline supervision software





Usability

- Flawless communication with all diffractometers
- Capacity to accommodate various standards of sample supports
- Automatic procedures for easy operation and maintenance (Dewar automatic drying, puck-loading assistance ...)



Safety

- Smart anti-collision system
- Next generation robot arm with builtin collaborative functions
- Vision control

Release: January 2025

Technical data

Key figures

Man-Machine

Others

Sample exchange time < 10 s

29 pucks in ∅700 mm (vacuum-insulated Dewar)
Storage capacity 464 samples with Unipuck

(With individual puck detection by electrical switches)

Automatic with continuous level probe

Sample picking success rate > 99.9%

Technical characteristics

Standards accommodated Unipuck, SC3 pucks, Spine and MiniSpine (Non-Spine magnetic caps upon request)

SBS plate

LN₂ refilling system

Low- and high-level alarms

Phase separator

LN₂ consumption ~2 L/h

Gripper(s) calibration Automatic within ± 30 μm accuracy

Environment teaching Automatic within ± 80 µm accuracy

Smart current monitoring of robot arm for anti-collision
Automatic recovery procedures
Safety & risk prevention
Sample detection inside gripper
Tool (gripper) identification ★

Restricted zone programming (safe zone) *

collaboration Safe limit speed, safe stop, safe tools & safe touch

Automatic Dewar drying for maintenance ★

Maintenance Remote access for maintenance and troubleshooting ★

System status indicators and warning alarms ★

High-definition surveillance camera ★ for:

Vision features

Pucks and samples presence detection inside the Dewar

Incident detection, process optimisation and diagnosis

Assistance for puck loading ★ inside the Dewar with puck barcode reading

Optional SIL3-PLe safety ★

Assistance for plate loading ★ with plate barcode reading Room-temperature puck(s) for mounting/unmounting specific tools on the diffractometer or into the beam path.

Automatic management of various sample loading positions.

Automatic management of various sample loading positions in a given volume

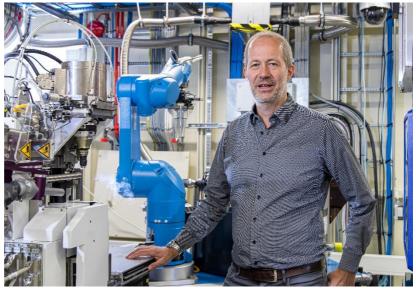
Communication Via Ethernet by means of TCP/IP sockets

Weight & Dimensions M = 590 kg L x W x H = 1240 x 700 x 2230 mm

★ New features available with ISARA2

Release : January 2025

An efficient teammate



© BioMAX experimental station at MAX IV Laboratory, Lund, Sweden

Since 2007, IRELEC's robotic sample changers have become the preferred choice for the automation of X-ray diffraction experiments on Synchrotron macro-molecular crystallography (MX) beamlines.

First CATS, then ISARA, have created a new standard for MX sample changers, whether in terms of high throughput capabilities, reliability or user-friendliness.

While building on these strengths, ISARA2 still improve the beamline uptime with unique features that both improve the whole process reliability and minimize the required human intervention during the normal use, further to an incident and for routine maintenance operations.

ISARA2 is a smart system, its software architecture and integrated sensors enable:

- to detect and recover automatically errors, so as to always preserve the manipulated samples
- to define exclusion areas, so as to protect the equipment and the surrounding high value devices
- o to assist the users when operating the system:
 - Visualization and detection of proper puck loading
 - Sample detection inside the Dewar
 - Automated maintenance procedures
 - Remote maintenance gateway for assistance.

ISARA2 is flexible system which is specifically built to interface with any end-station configuration and that can be smoothly integrated with all supervision beamline software.

ISARA users' community

MAX IV (BioMAX & MicroMAX) | BESSY II (BL14.2) | ALBA (XAIRA & XALOC) | CLS (CMCF-ID) | PLS II (BL 5C) | TPS (BL 05A & 07A) | SSRF (MPX) | APS (LRL-CAT) | NSLS II (NYX) | Australian Synchrotron (MX3 & MX2) | ...

CATS users' community

BESSY II (BL14.1) | SLS | DLS | APS (LS-CAT) | ALBA (XALOC) | SOLEIL (PX1 & PX2) | MAX II | SSRF (BL17B) | PLS II (BL 11C)

Release: January 2025

Customer testimonials

Dr Uwe MUELLER

Beamline Scientist at the HZB Macromolecular Crystallography Group

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ISARA and ISARA2 are very reliable, high performance research infrastructures, which play an important role for the success of the user program of our MX beamlines at HZB and elsewhere.

"

Dr Tom CARADOC-DAVIES

Lead scientist / MX3 beamline at the Australian Synchrotron

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Irelec staff were very accommodating and the delivered system is excellent. They are very professional and are open to discussing changes and modifications. They get the fine balance between meeting our local needs and keeping the robot [ISARA2] reliable and stable.

"

Dr Kevin BATTAILE Director of NYX beamline at

NSLS-II

Everything worked great with the robot [ISARA2] last run and I am very happy with how it is performing.

"

Dr Oskar AURELIUS Researcher at MAX IV Laboratory

The ISARA2 system delivered to the MicroMAX beamline at the MAX IV Laboratory, provided a sample changer solution with a swift sample exchange time, that could smoothly be integrated into the beamline environment.

"



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